



Plasma shape control with XSC during the ramp-up and ramp-down phases

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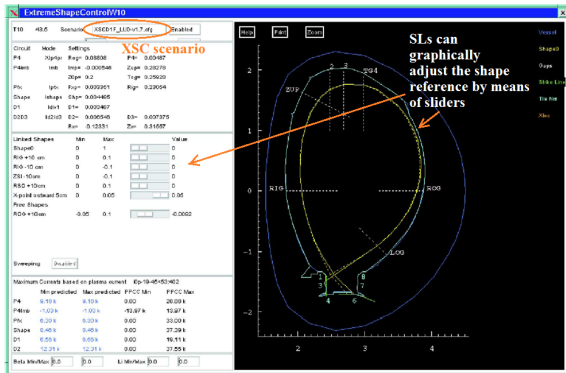


Outline

- 1 Px-2.1.7 – Backgrounds
- 2 Shape control during I_p ramp-up
- 3 Shape control during I_p ramp-down



XSC and CLA



- The XSC allows the SLs to directly specify the target shape, without specifying the PF current waveforms
- The PF current waveforms are *automatically* computed by the model-based control algorithm
- The PF currents may saturate during the experiment
- The Current Limit Avoidance System (CLA) has been recently designed and implemented **to avoid current saturations in the PF coils when the XSC is used to control the plasma shape**



Aims of Px-2.1.7

The main aims of Px-2.1.7 are:

- to apply the CLA to realistic plasma scenarios in condition of low disruption probability and low forces at disruption
- to show that the **CLA can enlarge the operational space of the XSC**
 - ① when the nominal currents in the PF coils are close to their limits and XSC has no margin for plasma boundary control
 - ② when large variations of β_p and I_i push the currents requested by the XSC close to their limits (**variations of I_p , I_i and β_p are seen as disturbances by the plasma shape control**)



Px-2.1.7 - Experiment #2 - 18 May 2012

- The early session on **Friday 18th May** was aimed to study the behavior of XSC+CLA during plasma current **ramp-up** and **ramp-down**
- This session was aimed to perform a preliminary assessment of the CLA performance during a variation of I_p
- **As important “by-product”, the first pulse ever in full XSC control has been run** [▶ Jotter pulse 83014](#)
- More details (pulse list, comments, etc.) can be found on the [▶ wiki page](#)



Comparison between SC and XSC

The following pulses are considered in order to compare the behavior of the two plasma shape controllers during the I_p ramp-up

- #83011 – with SC
- #83014 – with XSC

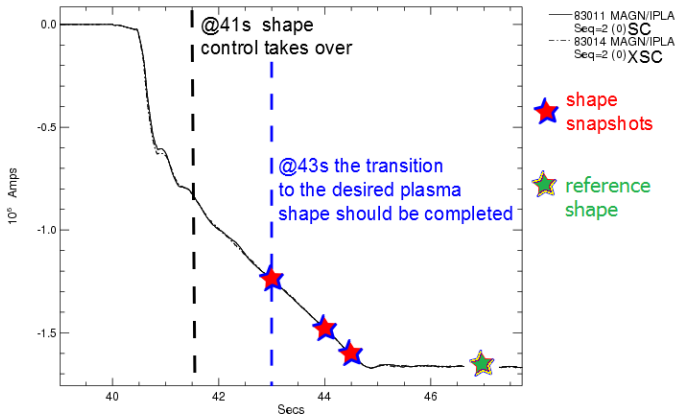
while the comparison during the I_p ramp-down is done considering the pulses

- #72203 – with SC
- #83014 – with XSC


 Pulses #83011 and #83014 - I_p ramp-up

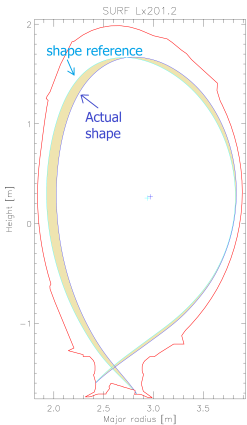
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Conf. V50H


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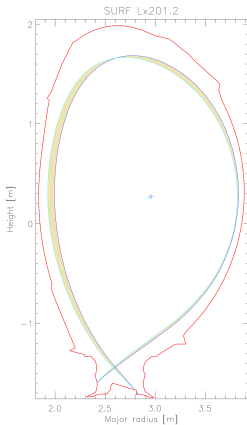


#83011 - Shape tracking during the ramp-up with SC



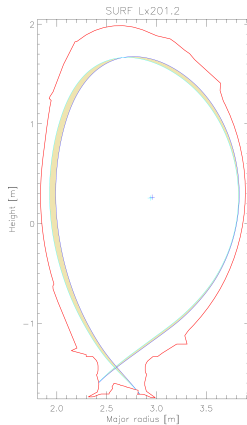
— #83011/JETPPF/EFIT/O t=43.013000
 — #83011/JETPPF/EFIT/O t=47.010601

@43s



— #83011/JETPPF/EFIT/O t=44.000999
 — #83011/JETPPF/EFIT/O t=47.010601

@44s



— #83011/JETPPF/EFIT/O t=44.502602
 — #83011/JETPPF/EFIT/O t=47.010601

@44.5s

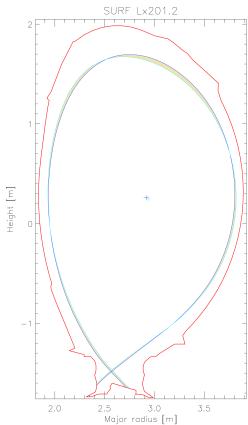


#83011 - Comments

- **Bad shape control in the inner side.**
- This is mainly due to the fact that P4 is used to control ROG, while RIG is not controlled

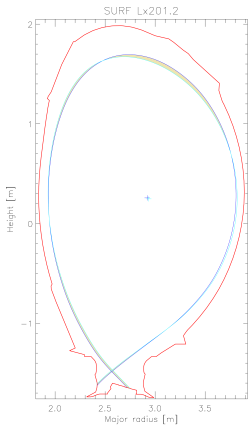


#83014 - Shape tracking during the ramp-up with XSC



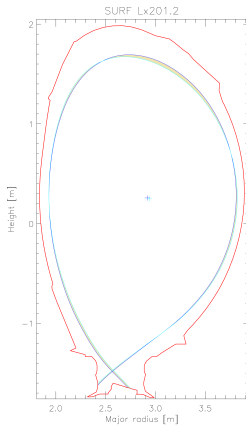
— #83014/JETPPF/EFIT/O t=43.013000
 — #83014/JETPPF/EFIT/O t=47.010601

@43s



— #83014/JETPPF/EFIT/O t=44.000999
 — #83014/JETPPF/EFIT/O t=47.010601

@44s



— #83014/JETPPF/EFIT/O t=44.502602
 — #83014/JETPPF/EFIT/O t=47.010601

@44.5s

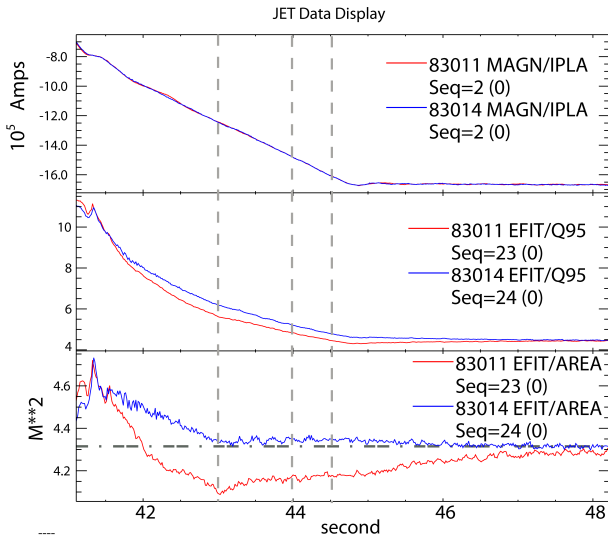


#83014 - Comments

- The biggest error in shape control is in the top outer region (remember the XSC minimizes the shape error in least mean square sense!)
- This error could be reduced by increasing the error in a different region (i.e. in the divertor region)
- Good shape tracking in both RIG and ROG regions, and good tracking of strike points and x-point position
- **By using the XSC the transition time can be further reduced, i.e. the desired plasma shape can be achieved about 1s earlier during the ramp-up (at 42s)**



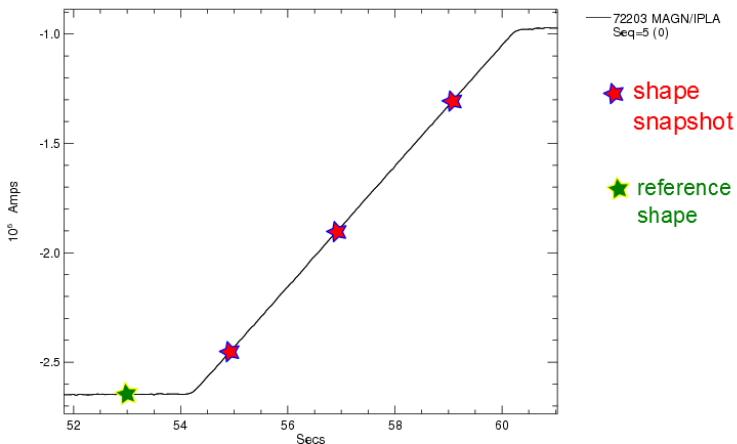
Plasma surface and q95





Pulse #72203 - I_p ramp-down with SC

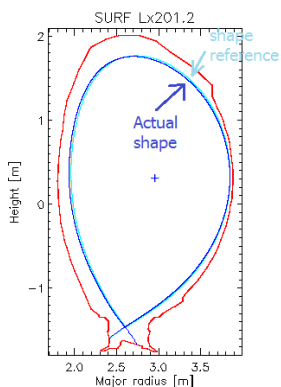
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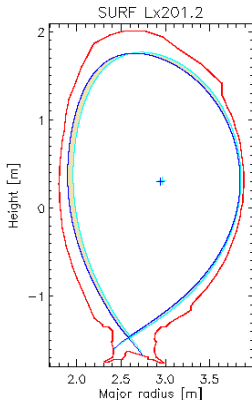


#72203 - Shape tracking during the ramp-down with SC



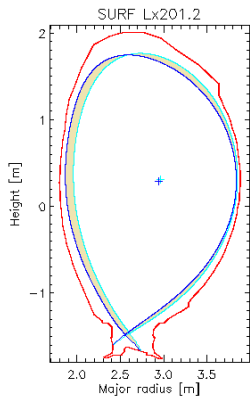
— #72203/JETPPF/EFIT/0.1
— #72203/JETPPF/EFIT/0.1

@55s



— #72203/JETPPF/EFIT/1
— #72203/JETPPF/EFIT/1

@57s



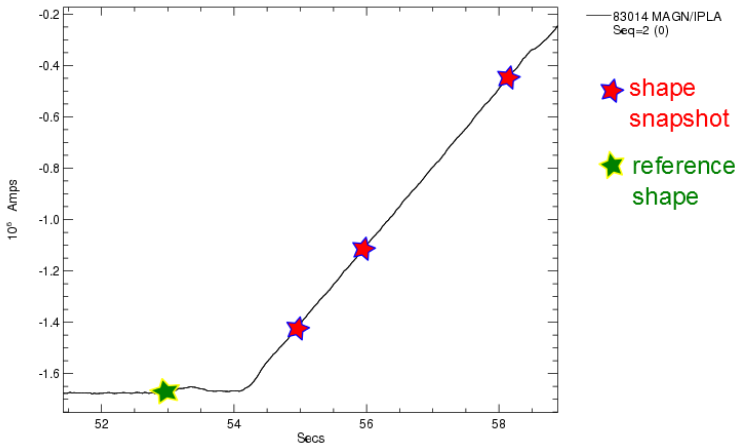
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— #72203/JETPPF/EFIT/1

@59s



Pulse #83014 - I_p ramp-down with XSC

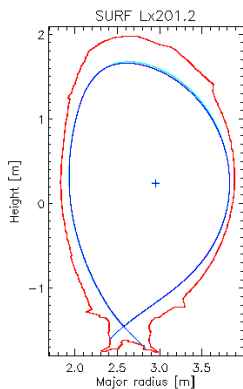
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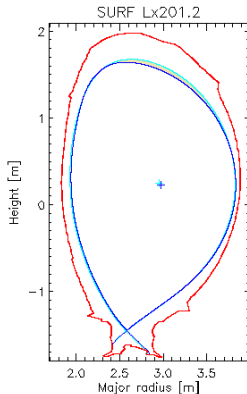


#83014 - Shape tracking during the ramp-down with SSC



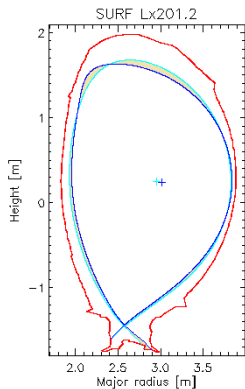
— #83014/JETPPF/EFIT/0
 — #83014/JETPPF/EFIT/0

@55s



— #83014/JETPPF/EFIT/0
 — #83014/JETPPF/EFIT/0

@56s



— #83014/JETPPF/EFIT/0
 — #83014/JETPPF/EFIT/0

@58s



Comments

- Also during I_p ramp-down, XSC has demonstrated to better controls the shape
- As for the use of the CLA during the ramp-down (when PF currents approach 0), the following **preliminary considerations need to be further investigated**:
 - the use of CLA with 0 low limits seems to delay the soft stop, hence to enlarge the XSC operational space
 - this improvement seems increase when the derivative of I_p is increased



Conclusions

- By using XSC a better control of plasma shape can be achieved during both I_p ramp-up and ramp-down
- Thanks to the CLA safe operations are guaranteed
- **Although only ohmic ramp-up/ramp-down have been run with XSC, simulations have been performed also for high confinement scenarios with β_p variations**
- **The use of XSC+CLA is recommended during I_p ramp-up and ramp-down, where large variations of I_p , I_i and β_p are expected**



Reference

eXtreme Shape Controller (XSC)



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Plasma shape control for the JET tokamak

IEEE Control Systems Magazine vol. 25, no. 5, pp. 65–75, Oct. 2005



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Current Limit Avoidance (CLA)



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