Non-local BV functions and a denoising model with  $L^1$  fidelity

# Giorgio Stefani

### (in collaboration with Konstantinos Bessas)

Shape Optimization, Geometric Inequalities, and Related Topics

January 31, 2023 Napoli







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Original



Noisy image



Denoised image



Source: Wikipedia

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Total variation denoising models

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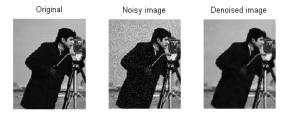


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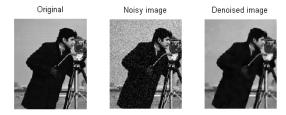
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where  $p \in [1, \infty)$  and  $\Lambda > 0$  is the fidelity.

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Applications: gravitational-waves (2018) and black hole in Messier 87 galaxy (2019)

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- > preserves sharp discontinuities (edges), removes fine scale details
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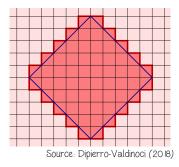
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<u>Others:</u> [Buades-Coll-Morel], [Kindermann-Osher-Jones], [Gilboa-Osher], [Antil-Diíaz-Jing-Schikorra] using [Comi-S.] and more...

STEP 0. We choose a kernel  $K \ge 0$  and define the (non-local total) K-variation

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STEP 3. We study the associated non-local Cheeger problem.

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#### **Basic** properties

- isometries:  $[\cdot]_{\mathcal{K}}$  is translation invariant, homogeneous and  $[c]_{\mathcal{K}}=0$
- min-max:  $[u \land v]_{\mathcal{K}} + [u \lor v]_{\mathcal{K}} \le [u]_{\mathcal{K}} + [v]_{\mathcal{K}}$
- Fatou:  $u_k \to u$  in  $L^1_{\text{loc}}(\mathbb{R}^n) \implies [u]_K \leq \liminf_k [u_k]_K$

• coarea formula: 
$$[u]_{\mathcal{K}} = \int_{\mathbb{R}} P_{\mathcal{K}}(\{u > t\}) dt$$

•  $BV \subset BV^{\kappa}$ :  $[u]_{\kappa} \leq \max\left\{\|u\|_{L^{1}}, \frac{1}{2}[u]_{BV}\right\} \int_{\mathbb{R}^{n}} (1 \wedge |x|) K(x) dx$ 

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Open problem: find isoperimteric sets for  $K \notin L^1$  NOT radially symmetric!

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$$P_{\mathcal{K}}(E) = \int_{0}^{\|\mathcal{K}\|_{L^{\infty}}} |E| |\{\mathcal{K} > t\}| - \int_{\mathbb{R}^{n}} \int_{\mathbb{R}^{n}} \mathbf{1}_{E}(x) \mathbf{1}_{E}(y) \mathbf{1}_{\{\mathcal{K} > t\}}(x-y) \, dx \, dy \, dt$$

$$P_{\mathcal{K}}(E) = P_{\mathcal{K}}(x) = P_{\mathcal{K}(x) = P_{\mathcal{K}}(x) = P_{\mathcal{K}}($$

noticing that  $\{K > t\} = B_{R(t)}$  is a ball for some  $R(t) \in [0, \infty]$ .

Open problem: find isoperimteric sets for  $K \notin L^1$  NOT radially symmetric!

#### Corollary [Bessas-S.]

K radially symmetric decreasing  $\implies [u]_{K} \ge [u^{\star}]_{K}$ 

equality  $\iff u \ge 0, \{u > t\}$  is a ball, if K radial<sup>+</sup> in a number of the origin

where  $u^{\star}$  is the symmetric decreasing rearrangement of u (apply coarea formula).

Assume K is q-decreasing:  $|x| \le |y| \implies K(x)|x|^q \ge K(y)|y|^q$  for  $q \ge 0$ .

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<u>Fun fact</u>: q-decreasing for  $q \ge n + 1 \implies BV^{K}$  functions are constant! [Brezis]

Assume K is *q*-decreasing:  $|x| \le |y| \implies K(x)|x|^q \ge K(y)|y|^q$  for  $q \ge 0$ . Fun fact: *q*-decreasing for  $q \ge n+1 \implies BV^K$  functions are constant! [Brezis]

Monotonicity [Bessas-S.]: 
$$0 < r \le R < +\infty \implies \frac{P_{\kappa}(rE)}{|rE|^{2-\frac{q}{n}}} \ge \frac{P_{\kappa}(RE)}{|RE|^{2-\frac{q}{n}}}$$

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Idea of proof: Observe that (for simplicity, K is symmetric)

$$P_{K}(\lambda E) = \int_{\lambda E} \int_{(\lambda E)^{c}} K(x - y) \, dx \, dy = \lambda^{2n} \int_{E} \int_{E^{c}} K(\lambda(x - y)) \, dx \, dy$$

for  $\lambda > 0$  by changing variables, then apply *q*-decreasing assumption.

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Isoperimetric inequality for small volumes [Bessas-S.]

K radial and 
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:  $|E| \le |B| \implies \frac{P_{K}(E)}{|E|^{2-\frac{q}{n}}} \ge \frac{P_{K}(B)}{|B|^{2-\frac{q}{n}}}$ 

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Gagliardo-Nirenberg-Sobolev for finite support [Bessas-S.]

 $u \in BV^K$  with  $|\operatorname{supp}(u)| < \infty \implies ||u||_{L^{\frac{n}{2n-q},l}} \leq C_{n,q,|\operatorname{supp}(u)|}^{iso}[u]_K$ .

Assume K is radial, 1-decreasing and 
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$$|E| < \infty \implies P_{\mathcal{K}}(E \cap C) \le P_{\mathcal{K}}(E)$$
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 $P_{\mathcal{K}}(E) - P_{\mathcal{K}}(E \cap H) \geq P_{\mathcal{K}}(F; B_{\mathcal{R}}(x_0)) - P_{\mathcal{K}}(H; B_{\mathcal{R}}(x_0))$ 

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where  $F = E \cup H$  and

$$P_{K}(F;A) = \left(\int_{E \cap A} \int_{E^{c} \cap A} + \int_{E \cap A} \int_{E^{c} \cap A^{c}} + \int_{E \cap A^{c}} \int_{E^{c} \cap A} \right) K(x-y) \, dx \, dy$$

is the K-perimeter of F relative to A.

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H is a half-space,  $0 \in \partial H \implies P_{K}(H; B_{R}) \leq P_{K}(E; B_{R})$  if  $E \setminus B_{R} = H \setminus B_{R}$ 

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*K*-Archimedes:  $A \subset B$  with A convex and  $|B| < +\infty \implies P_{K}(A) \leq P_{K}(B)$ 

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(FP) 
$$\min_{u \in L^1_{\text{loc}}(\mathbb{R}^n)} [u]_{BV^{\kappa}} + \Lambda \int_{\mathbb{R}^n} |u - f| \, d\nu$$

where  $\nu \in \mathcal{W}(\mathbb{R}^n) = \{\nu = w \mathscr{L}^n : w \in L^{\infty}, \text{ inf}_{\mathbb{R}^n} w > 0\}$  an  $L^{\infty}$ -weight measure.

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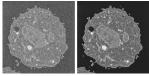
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#### Why $L^{\infty}$ -weight measures?

 $\rightsquigarrow$  deep learning

- $\blacktriangleright$  do not alter the  $L^1$  nature of the approximation term
- more flexibility, adding a degree of freedom in the fidelity
- $ightarrow \Lambda > 0$  keeps its role of global Lagrangian multiplier
- $\blacktriangleright \nu$  secondary local fidelity parameter (emphasis on specific regions only)



Source: Sun-Parwani

# Existence and basic properties for (FP)

Call  $FSol(f, A, \nu)$  the set of solutions of the functional problem

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$$\min_{u \in L^{I}_{\text{loc}}(\mathbb{R}^{n})} [u]_{BV^{K}} + \Lambda \int_{\mathbb{R}^{n}} |u - f| \, d\nu$$

Existence for (FP) [Bessas-S.]

 $K \notin L^{1}(\mathbb{R}^{n}), K \in L^{1}(\mathbb{R}^{n} \setminus B_{r}) \text{ for all } r > 0 \implies \mathsf{FSol}(f, \Lambda, \nu) \neq \emptyset \text{ for } f \in L^{1}(\mathbb{R}^{n})$ 

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#### Basic properties of F-solutions

▶ FSol(
$$f, \Lambda, \nu$$
) ⊂  $L_{loc}^1$  is convex and closed  
▶  $u_j \in FSol(f_j, \Lambda, \nu), f_j \to f$  in  $L^1, u_j \to u$  in  $L_{loc}^1 \implies u \in FSol(f, \Lambda, \nu)$   
▶ FSol( $f + c, \Lambda, \nu$ ) = FSol( $f, \Lambda, \nu$ ) +  $c$   
▶ FSol( $cf, \Lambda, \nu$ ) =  $cFSol(f, \Lambda, \nu)$   
▶  $u \in FSol(f, \Lambda, \nu) \implies u^+ \in FSol(f^+, \Lambda, \nu), u^- \in FSol(f^-, \Lambda, \nu)$   
▶  $u \in FSol(f, \Lambda, \nu) \implies u \land c \in FSol(f \land c, \Lambda, \nu), u \lor c \in FSol(f \lor c, \Lambda, \nu)$ 

We also study the geometric K-variation  $L^1$  denoising problem ( $f = \chi_E$ ,  $u = \chi_U$ )

(GP) 
$$\min_{U \subset \mathbb{R}^n} P_{\mathcal{K}}(U) + \Lambda \nu(U \bigtriangleup E)$$

and we let  $GSol(E, \Lambda, \nu)$  be set of solutions to the geometric problem.

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Basic properties of G-solutions

► 
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► 
$$U_j \in GSol(E_j, \Lambda, \nu), E_j \rightarrow E \text{ in } L^1, U_j \rightarrow U \text{ in } L^1_{loc} \implies U \in GSol(E, \Lambda, \nu)$$
  
►  $U \in GSol(E, \Lambda, \nu) \implies U^c \in GSol(E^c, \Lambda, \nu)$ 

- $GSol(E, \Lambda, \nu)$  closed under finite intersection and finite union
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#### Relation between F-solutions and G-solutions

▶ 
$$u \in FSol(f, \Lambda, \nu) \implies \{u > t\} \in GSol(\{f > t\}, \Lambda, \nu) \text{ for all } t \in \mathbb{R} \setminus \{0\}$$
  
▶  $\{u > t\} \in GSol(\{f > t\}, \Lambda, \nu) \text{ for a.e. } t \in \mathbb{R} \implies u \in FSol(f, \Lambda, \nu)$ 

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Moreover, if  $|\mathbf{E}| < \infty$ , then:

► 
$$U \in GSol(E, \Lambda, \nu) \implies \chi_U \in FSol(\chi_E, \Lambda, \nu)$$

► 
$$u \in FSol(\chi_E, \Lambda, \nu) \implies 0 \le u \le 1$$
 a.e.,  $\{u > t\} \in GSol(E, \Lambda, \nu)$  for  $t \in (0, 1)$ 

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 $K \notin L^1(\mathbb{R}^n), K \in L^1(\mathbb{R}^n \setminus B_r) \text{ for all } r > 0 \implies GSol(E, \Lambda, \nu) \neq \emptyset \text{ for } |E| < \infty$ 

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(1)  $E \subset B_R \implies U \subset B_R$  for all  $U \in GSol(E, \Lambda, \nu)$ 

Moreover, if also  $K \notin L^1$ , then

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Idea of proof:

(1)  $\nu((U \cap B_R) \cap E) \leq \nu(U \cap E)$  and  $P_K(U \cap B_R) \leq P_K(U)$ , since  $B_R$  convex.

#### Existence for (GP) [Bessas-S.]

 $K \notin L^1(\mathbb{R}^n), K \in L^1(\mathbb{R}^n \setminus B_r) \text{ for all } r > 0 \implies \text{GSol}(E, A, \nu) \neq \emptyset \text{ for } |E| < \infty$ 

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(2) Consider monotone maps  $\Lambda \mapsto \inf / \sup \{ \|u - \chi_E\|_{L^1(\nu)} : u \in FSol(\chi_E, \Lambda, \nu) \}$ . Prove that  $FSol(\chi_E, \Lambda, \nu) = \{u_\Lambda\}$  for  $\Lambda > 0$  outside countable jump set. Observe that  $u = \chi_U$  for some  $U \subset E$  by basic properties. Since  $FSol(\chi_E, \Lambda, \nu)$  is convex, U is unique.

#### Existence of max and min solutions of (GP) [Bessas-G.]

Assume  $K \notin L^1(\mathbb{R}^n)$ ,  $K \in L^1(\mathbb{R}^n \setminus B_r)$  for all r > 0. If  $|E| < \infty$ , then (GP) admits a minimal and a maximal solution  $E^-, E^+ \in GSol(E, \Lambda, \nu)$  w.r.t. inclusion.

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Assume  $K \notin L^1(\mathbb{R}^n)$ ,  $K \in L^1(\mathbb{R}^n \setminus B_r)$  for all r > 0, K symmetric and K > 0. If  $P_K(E_i) < \infty$  and min $\{|E_i|, |E_i^c|\} < \infty$  for i = 1, 2, then

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<u>Remark</u> K > 0 can be weaken to get a comparison principle at small scales.

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Let E be  $C^{1,1}$  regular open set with min $\{|E|, |E^c|\} < \infty$ . There is  $\overline{\Lambda} > 0$  such that  $GSol(E, \Lambda, \nu) = \{E\}$  and  $GSol(E^c, \Lambda, \nu) = \{E^c\}$  for all  $\Lambda > \overline{\Lambda}$ .

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High fidelity for uniformly  $C^{1,1}$  regular functions [Bessas-S.]

Let  $f \in L^1$  have uniformly  $C^{1,1}$  regular superlevel sets. There is  $\overline{\Lambda} > 0$  such that

 $FSol(f, \Lambda, \nu) = \{f\}$  for all  $\Lambda > \overline{\Lambda}$ .

uniformly  $C^{1,1}$  regular superlevels = inner/outer radius of  $\{f > t\}$  uniform in  $t \in \mathbb{R}$ 

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For R < D/4 there is  $\overline{\Lambda} > 0$  such that

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The trick is to estimate  $[u]_{K} \gtrsim_{h} ||u(\cdot + h) - u||_{L^{1}} = 2||u||_{L^{1}} \gtrsim_{\nu} ||u||_{L^{1}(B_{R},\nu)}$  for  $2R \leq |h| \leq \frac{D}{2}$ .

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$$|u(x) - u(y)| \le \omega_{K,D}(|x - y|) \left( \mathbf{D}_{K}u(x) + \mathbf{D}_{K}u(y) \right),$$
$$\mathbf{D}_{K}u(x) = \frac{1}{2} \int_{\mathbb{R}^{n}} |u(x) - u(z)| K(x - z) dz \quad \text{and} \quad \omega_{K,D} \text{ modulus of continuity}$$

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Let K radial,  $K \in L^{1}(\mathbb{R}^{n} \setminus B_{r}) \forall r > 0$ ,  $K \notin L^{1}$  and q-decreasing with q < n + 1. Cheeger sets E exist (hence  $h_{K,\nu}(\Omega) > 0$ ) with

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The Cheeger problem for the K-variation in an admissible  $\Omega \subset \mathbb{R}^n$  with  $|\Omega| < \infty$  is

$$h_{K,\nu}(\Omega) = \inf\left\{\frac{P_{K}(E)}{\nu(E)} : E \subset \Omega, \ |E| \in (0,\infty)\right\} \in [0,\infty)$$

We call  $h_{K,\nu}(\Omega)$  the Cheeger constant of  $\Omega$  and any minimizer a Cheeger set of  $\Omega$ .

#### Existence of Cheeger sets and basic properties [Bessas-S.]

Let K radial,  $K \in L^1(\mathbb{R}^n \setminus B_r) \ \forall r > 0$ ,  $K \notin L^1$  and q-decreasing with q < n + 1. Cheeger sets E exist (hence  $h_{K,\nu}(\Omega) > 0$ ) with

$$|E|^{\frac{q}{n}-1} \geq C_{|\Omega|,n,q,\nu}^{iso} h_{K,\nu}(\Omega).$$

Moreover,  $\partial E \cap \partial \Omega \neq \emptyset$  for  $\nu = \mathscr{L}^n$ ,  $\Omega$  open and K *n*-decreasing<sup>+</sup>.

Idea of proof: exploit compactness in  $BV^{\kappa}$ , isoperimetric ineq. and monotonicity.  $\Box$ 

Further properties for  $\nu = \mathscr{L}^n$  [Bessas-S.]

- ► calibrability: balls are self-Cheeger sets
- ► *K*-Faber-Krahn inequality:  $h_{\mathcal{K}}(\Omega) \ge h_{\mathcal{K}}(B^{|\Omega|})$  where  $|B^{|\Omega|}| = |\Omega|$

Assume K radial,  $\int_{\mathbb{R}^n} (1 \wedge |x|) K(x) dx < \infty$ ,  $K \notin L^1(\mathbb{R}^n)$ , K q-decreasing with  $q \in [1, n + 1)$  and D-doubling with  $D = \infty$ .

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Relation between (GP) and Cheeger problem [Bessas-S.]

Let E be a bounded convex set with non-empty interior.

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Relation between (GP) and Cheeger problem [Bessas-S.]

Let *E* be a bounded convex set with non-empty interior.

(1)  $h_{K,\nu}(E) = \sup\{\Lambda > 0 : \emptyset \in GSol(E,\Lambda,\nu)\} \in (0,\infty).$ 

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(3)  $\Lambda = h_{K,\nu}(E) \implies GSol(E,\Lambda,\nu) = C_{K,\nu}(E) \cup \{\emptyset\}$  and so

 $\mathsf{FSol}(\chi_E, h_{K,\nu}(E), \nu) = \left\{ u \in \mathcal{BV}^K(\mathbb{R}^n; [0,1]) : \{u > t\} \in \mathcal{C}_{K,\nu}(E) \cup \{\emptyset\} \right\}$ 

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Relation between (GP) and Cheeger problem [Bessas-S.]

Let *E* be a bounded convex set with non-empty interior.

(1) 
$$h_{K,\nu}(E) = \sup\{A > 0 : \emptyset \in GSol(E, A, \nu)\} \in (0, \infty).$$
  
(2)  $A < h_{K,\nu}(E) \implies GSol(E, A, \nu) = \{\emptyset\}.$   
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(4)  $A > h_{K,\nu}(E)$  and E is calibrable  $\implies GSol(E, A, \nu) = \{E\}$ 

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(4)  $\Lambda > h_{K,\nu}(E)$  and *E* is calibrable  $\implies GSol(E,\Lambda,\nu) = \{E\}.$ 

For  $\nu = \mathcal{L}^n$  and E = ball B, such result can be improved as

$$GSol(B, \Lambda, \mathscr{L}^n) = \begin{cases} \{\emptyset\} & \text{for } \Lambda < \Lambda_0 \\ \{\emptyset, B\} & \text{for } \Lambda = \Lambda_0 \\ \{B\} & \text{for } \Lambda > \Lambda_0 \end{cases} \quad \text{where } \Lambda_0 = \frac{P_{\mathcal{K}}(B)}{|B|}$$

# THANK YOU FOR YOUR ATTENTION!

Slides available via giorgio.stefani.math@gmail.com or giorgiostefani.weebly.com.

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