

# Evaluating A New Proxy For Spectral Shape To Be Used As An Intensity Measure

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**Abstract.** The possibility to use a new vector-valued ground motion intensity measure (IM) is analyzed; it is based on the spectral acceleration at first mode ( $S_a$ ) and a parameter proxy for the spectral shape, namely  $N_p$ . The potential of the vector  $\langle S_a, N_p \rangle$  is explored by efficiency comparison with other IMs. It will be illustrated how the form of the vector  $\langle S_a, N_p \rangle$  may represent an improvement in predicting the seismic response in terms of ductility, dissipated hysteretic energy and Park and Ang damage index for nonlinear single degree of freedom (SDOF) structures subjected to ordinary, narrow-band and near-source pulse-like records.

**Keywords:** Intensity measures, scalar intensity measures, probabilistic seismic demand analysis, dissipated hysteretic energy, Park and Ang damage index, ductility displacement demand.

## INTRODUCTION

Due to all the uncertainties associated with the response of structures subjected to earthquakes, it is required a probabilistic approach. Probabilistic seismic demand analysis (PSDA) is used as a tool to estimate the reliability of structures subjected to earthquakes, through the evaluation of the mean annual frequency (MAF) of exceeding a specified value of an earthquake demand parameter (EDP) using the next equation:

$$\lambda_{EDP}(x) = \int \int \int_{IM, M, R} P[EDP > x | IM, M, R] f(IM | M, R) f(M, R) dr dm d(im) \quad (1)$$

where  $\lambda_{EDP}(x)$  is the MAF of EDP exceeding a value  $x$ ,  $f(IM | M, R)$  is the conditional distribution function of IM given magnitude ( $M$ ) and distance ( $R$ ), (e.g. an attenuation law).  $f(M, R)$  is the joint probability density function of  $M$  and  $R$ . Finally,  $P[EDP > x | IM, M, R]$  is the failure probability of the structure as a function of IM,  $M$  and  $R$ . If  $P[EDP > x | IM, M, R] = P[EDP > x | IM]$  then the IM is said *sufficient* [1, 2] since its ability to predict the structural response is independent of  $M$  and  $R$  given IM. An IM that shows good correlation with the structural response (e.g. small variability of EDP given IM) is said to be *efficient* [2]. A well chosen IM is important for the next reasons: 1) it can be used to joint the relation between seismologist and earthquake engineering, by decoupling the ground motion hazard and nonlinear dynamic analysis as suggested by Cornell and co-workers [1-3]; 2) it can avoid the need of a detailed

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ground motion record selection, and reduce the number of records used for computational analysis involved in PSDA [4]. In 1952, Housner [5] proposed to use the area under the velocity spectrum as an IM; twenty years later Von Thun et al [6] suggested the area under the acceleration spectrum in a range of period 0.1 to 0.5 to analyze dams. In the last years, the spectral acceleration at first mode ( $Sa(T_1)$ , here named also  $Sa$ ) became very popular, but due to its insufficiency in some cases [7] as predictor of EDPs; recently, other advanced both scalar and vector-valued IMs have been proposed. In particular, the vector  $\langle Sa, \varepsilon \rangle$  has resulted sufficient; efficient in many cases [7], but Tothong and Luco [8] showed its ineffectiveness to predict the response of structures subjected to pulse-like records, and they proposed an advanced scalar IM based on the inelastic spectral displacement. It results efficient for ordinary and pulse-like records, at least to predict interstory drifts; however, the application of this IM is more complicated. Another vectorial IM  $\langle Sa, R_{T_1, T_2} \rangle$  (based on the originally scalar proposed by Cordova et al [9], where  $R_{T_1, T_2}$  is the ratio between the spectral acceleration at period  $T_2$  divided by spectral acceleration at period  $T_1$ ), has resulted effective for pulse-like records [10]. Baker and Cornell [11] also explored how to avoid peaks or valleys using the geometrical mean of spectral acceleration in a range of periods,  $Sa_{avg}(T_1 \dots T_N)$ . It can be observed in all the IMs mentioned one important aspect: the efforts trying to propose different alternative IMs in many cases are concentrated in general on spectral shape, because its importance as a predictor of structural response [1-11]. (However, it is important to say that similar values of  $\langle Sa, R_{T_1, T_2} \rangle$ ,  $\langle Sa, \varepsilon \rangle$  and  $Sa_{avg}(T_1 \dots T_N)$  in some cases provoke different spectral shapes, and with this important differences in the response).

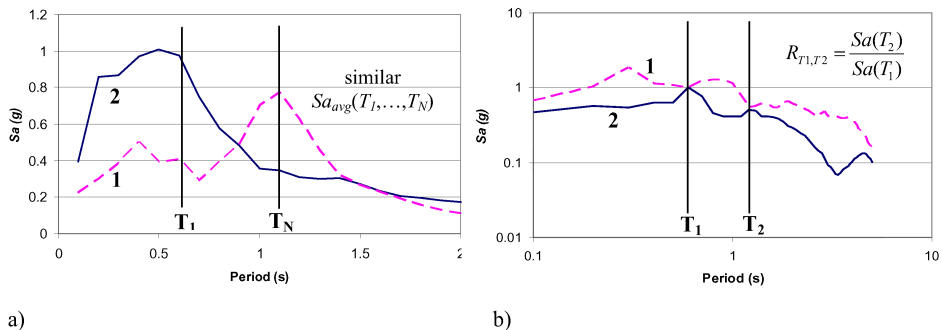
The motivation of this paper is to analyze a new vector-valued IM based on  $Sa$  and a parameter named  $N_p$ , for two reason: a) it is consistent with the spectral shape, and 2) the vector  $\langle Sa, N_p \rangle$  could be a good candidate to predict EDPs related not only with maximum also with energy demands (due to the importance for long duration ground motions or structures with low cyclic capacity [12-15]).

## SEISMIC RECORDS

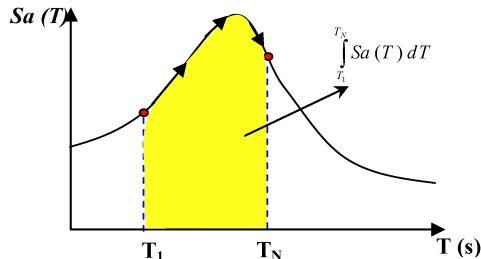
To the aim of the present paper, three sets of seismic records were considered to represent ordinary, near-source pulse-like and narrow-band motions. The set of ordinary 194 records used in a previous study [16, Table A.3; except Chi-Chi Taiwan] has closest distance to rupture between 15 and 95kms, and magnitudes from 5.65 to 7.90. The pulse-like records consist in a set of 48 motions with a pulse period close to 1s (mean  $Tp \approx 1.0s$ ). The records were rotated in the fault-normal direction. The earthquake magnitude range is from 5.6 to 7.6, and the closest distance to rupture less than 22kms. The pulse-like set is a subset of that in [17]. The ordinary and pulse-like records correspond to firm soil or rock. Due to narrow-band motions demand large energy amount to the structures compared to broad-band motions [14], they were also considered for the purposes of this study. A set of 31 ground motion records obtained from the soft-soil of the Valley of Mexico were used. The magnitude range is from 6.9 to 8.1 (including the 1985 Mexican Earthquake). The records previously used by [15] were selected for a soil period close to 2 seconds and correspond to far field.

## A NEW PROXY FOR SPECTRAL SHAPE TO BE USED AS AN IM

It has been mentioned that IMs in some cases can not represent with good accuracy the spectral shape. To clarify this, figure 1a shows two response spectra with similar values of  $Sa_{avg}(T_1 \dots T_N)$ , it is clear how the spectral shape of both records is completely different, which suggests that different responses will be obtained. Figure 1b illustrates the same case scaling to similar  $Sa$  and  $R_{T_1, T_2}$ , and it is because the path of the structure since its elastic behavior until it arrives to the maximum nonlinear behavior is not considered. In other words, there is no information about the spectral shape for periods larger than  $T_2$  and smaller than  $T_1$ . The idea of Housner and Von Thun to use the area under the acceleration spectrum in a range  $T_1$ - $T_N$  (figure 2) could be a good candidate to know the spectral shape, because it considers the path since the structure has a period  $T_1$  until it finishes with an elongated period of  $T_N$ , but to be consistent with the spectral shape, it is better to express the spectral area normalizing by  $Sa(T_1)$  and  $T_1$  to account for the position of the structure in the spectrum, and it lets introduce a new parameter named  $N_p$  (Eq. 2), which may give that in the most of the cases, similar values of this parameter provoke similar spectral shapes. It is also possible to approximate  $N_p$  as a function of geometrical mean of spectral acceleration in a range of periods interest (Eq. 2).



**FIGURE 1.** Elastic response spectra for two records a) scaled for the same geometrical mean  $Sa_{avg}(T_1, \dots, T_N)$  that reflects different spectral shapes; b) scaled for same values of  $Sa$  and  $R_{T_1, T_2}$  that also reflects different spectral shapes.



**FIGURE 2.** Example of an elastic response spectrum and the use of the area under the curve to characterize spectral shape.

$$N_p = \frac{1}{T_1 Sa(T_1)} \int_{T_1}^{T_N} Sa(T) dT \approx \frac{Sa_{avg}(T_1 \dots T_N) * (T_N - T_1)}{T_1 Sa(T_1)} \quad (2)$$

The term  $N_p$  in Eq. 3 was adopted, because it represents the contribution of  $N$  points of the spectrum. The normalizing between  $Sa(T_1)$  let  $N_p$  be independent of the scaling level of the records based on  $Sa(T_1)$ .

## EFFICIENCY OF DIFFERENT VECTOR-VALUES INTENSITY MEASURES

In this part, the efficiency of the vectors  $\langle Sa, \varepsilon \rangle$ ,  $\langle Sa, R_{T1,T2} \rangle$  and  $\langle Sa, N_p \rangle$  as predictors of the structural response is compared through the analyses of nonlinear SDOF. Three EDPs were studied. The first EDP considered here is the ductility displacement demand  $\mu_D$  (ratio of maximum displacement  $D_m$  and yielding displacement  $D_y$ ). The second is  $D_{hyst}$  (parameter based on normalized dissipated hysteretic energy by displacement and strength yielding  $F_y$ ) that captures information about the ground motion duration effects or cumulative demands [18].  $D_{hyst}$  is defined in Eq. 3.

$$D_{hyst} = 1 + \frac{E_H}{F_y D_y} \quad (3)$$

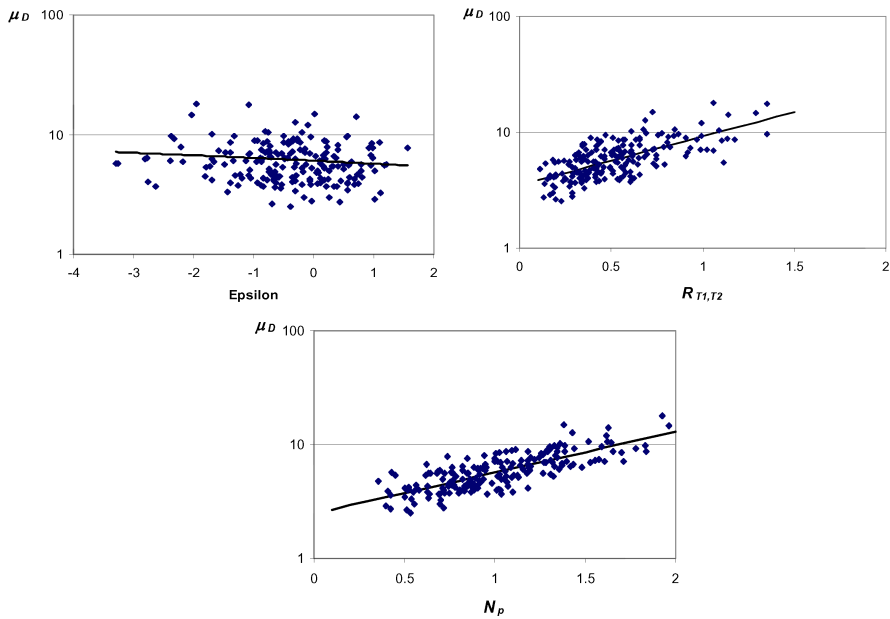
Finally, the last EDP considered is the well known Park and Ang damage index ( $I_{DPA}$ ) [19] for all the experimental evidence existing behind this parameter. The expression of  $I_{DPA}$  is illustrated in Eq. 4, in this equation  $\mu$  is the ductility capacity, and  $\beta$  is a parameter that represents the contribution of dissipated hysteretic energy to the damage, a value of  $\beta=0.15$  was used [20].

$$I_{DPA} = \frac{\mu_D}{\mu} + \beta \frac{E_H}{F_y D_y \mu} \quad (4)$$

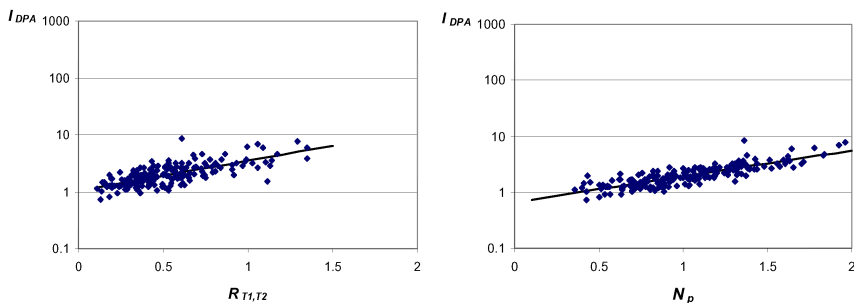
### Analyses for ordinary records

A SDOF with  $T=0.6s$  bilinear behavior, 5% of postyielding stiffness and 5% of critical damping was analyzed. First, the records were scaled for similar values of  $Sa(T_1)$  equals to  $1g$ , and then the relation between the second parameter of the vector and the different EDPs was obtained. Figure 3 shows the relation between  $\varepsilon$  (where epsilon was computed using the Boore and Atkinson [21] attenuation law),  $R_{T1,T2}$  and  $N_p$  with the displacement ductility demand. Figure 4 illustrates the results for  $R_{T1,T2}$  and  $N_p$  in respect to  $I_{DPA}$ . A good correlation exists with displacement ductility demands and  $I_{DPA}$ , especially for  $R_{T1,T2}$ , and  $N_p$ ; however, it is clear how the efficiency of  $N_p$  compared with  $R_{T1,T2}$  is moderately larger. Similar results were obtained for  $D_{hyst}$ , they are not included here for the sake of brevity, but the summary is given in table 1. It is observed the less dispersion for the vector  $\langle Sa, N_p \rangle$ , and this is valid in the prediction

of all the EDPs. For the case of ductility demands and  $\langle Sa, N_p \rangle$ , the dispersion is ( $\sigma_{ln}(\mu)=0.228$ ) which is reduced near to 50% compared for a scaling criterion based on  $Sa$  ( $\sigma_{ln}(\mu)=0.40$ ). This implies a reduction in the number of records required for the analyses. The value of  $T_2$  for  $R_{T_1, T_2}$  results 2 times  $T_1$  (similar to the value proposed by Cordova et al [9]) and  $T_N$  for  $N_p$  equals to  $2.5T_1$ , and they correspond to the optimal values obtained from the analyses (the values where the minimum standard deviation occurs). The results suggest that the best candidates are  $N_p$  and  $R_{T_1, T_2}$ , while  $\varepsilon$  results in larger dispersion for the EDPs considered.



**FIGURE 3.** Ductility prediction for a SDOF with  $T=0.6s$  ( $Sa=1g$ ) for: a) epsilon, b)  $R_{T_1, T_2}$  and c)  $N_p$ .



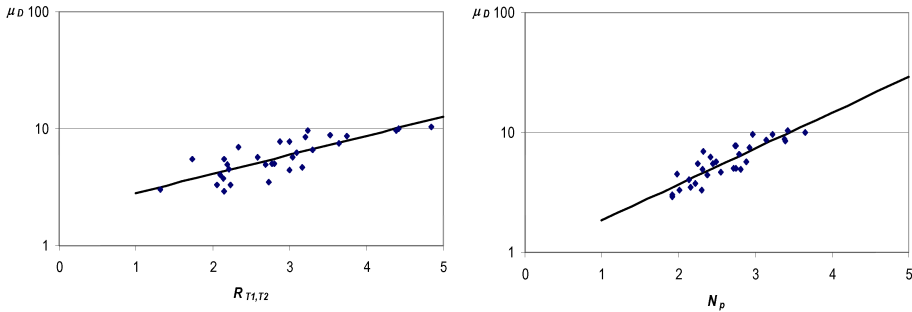
**FIGURE 4.**  $I_{DPA}$  prediction for a SDOF with  $T=0.6s$  ( $Sa=1g$ ) for: a)  $R_{T_1, T_2}$  and b)  $N_p$ .

**TABLE 1.** Standard deviations of the natural logarithmic for different IMs (ordinary records,  $Sa=1g$ ).

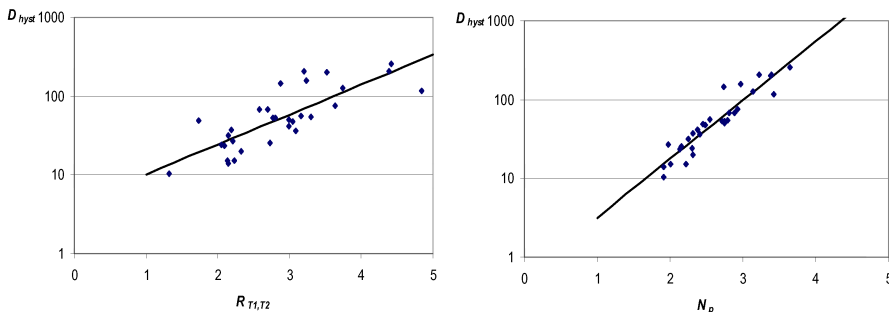
IM	$\sigma_m(\mu_n)$	$\sigma_m(D_{hyst})$	$\sigma_m(I_{DPA})$
$\langle Sa, N_p \rangle$	0.228	0.366	0.231
$\langle Sa, R_{T1,T2} \rangle$	0.260	0.414	0.259
$\langle Sa, \varepsilon \rangle$	0.365	0.497	0.341

## Narrow-Band Motions

For this case, a SDOF with a vibration period of 1s is analyzed. The relation between the different vectorial IMs and the EDPs  $\mu_D$  and  $D_{hyst}$  (except epsilon who shows low correlation with the response) are observed in figures 5 and 6. The higher correlation was observed for the vector based on  $Sa$  and  $N_p$ , and the efficiency of  $R_{T1,T2}$  as a predictor of cumulative demands is lower compared with the set of ordinary records. It can be observed in table 2, where the summary of results is illustrated, how the vector here proposed improves in the prediction of the EDPs considered compared with ordinary records. Results also show the improvement on the efficiency with respect to  $R_{T1,T2}$ , especially for the case of  $D_{hyst}$  where the reduction in the dispersion is around 50%. The dispersion of ductility demand in respect to  $\langle Sa, N_p \rangle$  is  $\sigma_m(\mu) = 0.185$ , which is 50% lower than that computed using  $Sa$  as an IM ( $\sigma_m(\mu) = 0.378$ ).



**FIGURE 5.**  $\mu_D$  prediction for a SDOF with  $T=1s$  ( $Sa=0.5g$ ) for  $R_{T1,T2}$  and  $N_p$ .



**FIGURE 6.**  $D_{hyst}$  prediction for a SDOF with  $T=1s$  ( $Sa=0.5g$ ) for  $R_{T1,T2}$  and  $N_p$ .

**TABLE 2.** Standard deviations for different IM (narrow-band motions,  $S_a=0.5g$ ).

IM	$\sigma_{in}(\mu_D)$	$\sigma_{in}(D_{hvsd})$	$\sigma_{in}(I_{DPA})$
$\langle Sa, N_p \rangle$	0.185	0.306	0.235
$\langle Sa, R_{T_1, T_2} \rangle$	0.229	0.531	0.375
$\langle Sa, \varepsilon \rangle$	0.368	0.766	0.585

### Near-Source Pulse-like Records

It has been observed that near source pulse-like records have an important influence on structures with a relation  $T_1/T_p=0.5$  [16]. Herein, a SDOF ( $T_1=0.5s$ ) was subjected to a set of 48 pulse-like records with  $T_p \approx 1.0s$ . For brevity only the summary of the results is given in table 3. In general, the efficiency of  $\langle Sa, N_p \rangle$  to predict EDPs is similar that in the case of narrow-band motions. As [10] suggests for pulse-like records, the vector  $\langle Sa, R_{T_1, T_2} \rangle$  is more efficient compared with the other sets studied. Nevertheless, as in the other cases, the efficiency of the vector  $\langle Sa, N_p \rangle$  continue been moderately larger compared with the other IMs in the prediction of all the EDPs.

**TABLE 3.** Standard deviations for the different IMs (near-source pulse-like records,  $S_a=0.9g$ ).

IM	$\sigma_{in}(\mu_D)$	$\sigma_{in}(D_{hvsd})$	$\sigma_{in}(I_{DPA})$
$\langle Sa, N_p \rangle$	0.253	0.224	0.169
$\langle Sa, R_{T_1, T_2} \rangle$	0.271	0.255	0.263
$\langle Sa, \varepsilon \rangle$	0.388	0.482	0.384

### CONCLUSIONS

The use of the new vector-valued IM based on  $S_a(T_1)$  and a proxy for spectral shape named  $N_p$  is explored by efficiency comparison with other IMs. It is observed how the vector  $\langle Sa, N_p \rangle$  show, at least moderately, larger efficiency in respect to the vector  $\langle Sa, R_{T_1, T_2} \rangle$  to predict displacement and energy demands in nonlinear SDOF subjected to ordinary records and pulse-like records. In general, the vectors  $\langle Sa, N_p \rangle$  and  $\langle Sa, R_{T_1, T_2} \rangle$  result better predictors compared with  $\langle Sa, \varepsilon \rangle$  for all the record sets considered. When the SDOF were subjected to narrow-band motions, the vector  $\langle Sa, N_p \rangle$  showed larger efficiency in respect to ordinary records and to the other IMs analyzed. For narrow-band motions, the efficiency of the vector  $\langle Sa, R_{T_1, T_2} \rangle$  to predict EDPs that account for energy demands is reduced in respect to the other record sets considered, while  $\langle Sa, N_p \rangle$  shows still a good correlation.

The results in general suggest that the vector  $\langle Sa, N_p \rangle$  seems to be a promising candidate to be an IM useful for predicting displacements and cumulative damage EDPs.

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